

Poor directional stability causes yaw motion and thus increases fuel consumption. Autopilot has a big influence on the course keeping ability. The best autopilots today are self tuning, adaptive autopilots.

Finding the correct autopilot parameters suitable for the current route and operation area will significantly reduce the use of the rudder and therefore reduce the drag.



Finding the correct parameters or preventing unnecessary use of the rudder gives an anticipated benefit of 1-5%.



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